

# 2016 DOE Vehicle Technologies Office Annual Merit Review and Peer Evaluation Meeting

# Multi-Speed Transmission for Commercial Delivery Medium Duty Plug-In Electric Drive Vehicles

Project ID: VS161

Principal Investigator: Bulent Chavdar Eaton Corporation June 9, 2016



"This presentation does not contain any proprietary, confidential, or otherwise restricted information."

### Overview

#### **Timeline**

Project Start Date: October 1, 2014

Project End Date: October 31, 2017

% Complete: 40%

Budget Period	Start Date	End Date
1	10/1/2014	10/31/2015
2	11/1/2015	10/31/2016
3	11/1/2016	10/31/2017

#### **Budget**

Project Value: \$3,749,710

DOE Share: \$2,428,655

• FFRDC: \$ 571,100

• Eaton Share: \$ 749,955 ( 20%)

DOE funding to Eaton: \$2,428,655

• BP1: \$ 497,660

BP2: \$1,171,089

BP3: \$ 759.906

#### **DOE** objectives

- The public acceptance of electric vehicles will be increased with a transmission
- The performance gap between EVs and ICDVs will be reduced with a transmission
- The concept transmission will be reliable, affordable, scalable and low weight

#### **Partners**

Prime: Eaton Corporation



- Subcontractors
  - New EV-OEM in BP2. (Smith Electric in BP1)
  - Oak Ridge National Laboratory
  - National Renewable Energy Laboratory

New EV-OEM







### Relevance for addressing barriers

#### Improving the Performance of EVs

Characteristic	Units	EV with SS	EV with MS Trans.	Target Improv.
Top speed	mph	55	65+	20%
Efficiency on UDDS	mpge	29.5	32	8%
Accel. (0-50 mph)	S	90	45	50%
Gearbox efficiency	%	93.4	98	5%

#### Reliable, efficient, affordable and low weight transmission

- Creating and validating a baseline 10 ton medium duty electric truck model.
- Benchmarking the baseline vehicle performance. Generating transmission concepts and selecting the best concept.
- Developing cost sensitive, high efficiency transmission by optimizing the number of gears, the gear ratios and the shift strategy.



## Approach/Strategy

### **Approach: Multi Speed Transmission helps**

- Close the performance gap with Internal Combustion Drive Vehicles by operating the motor at its peak efficiency region.
- Provide higher gradeability and faster acceleration with a low gear.
- Increase top speed and range with a high gear.
- By selecting efficient, lightweight, reliable, automated, or automatic transmission concept with novel shifting, clutching and controls systems.



### **Strategy**

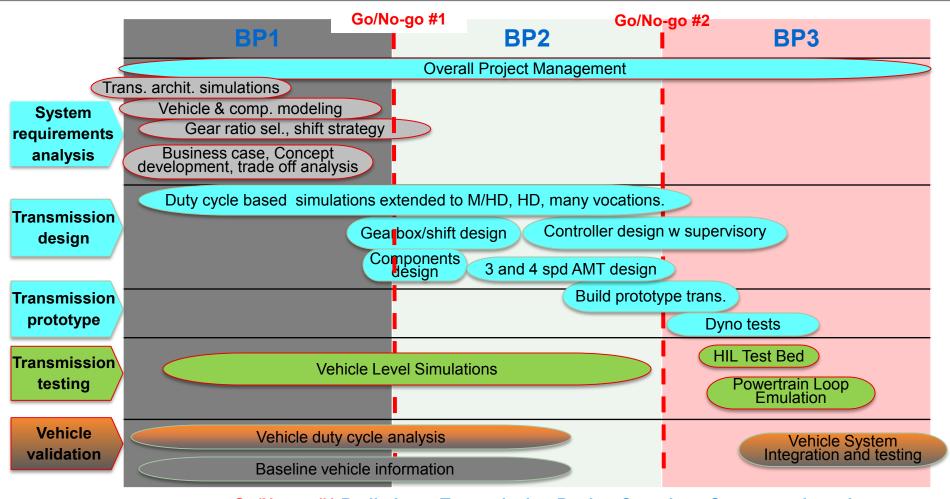
 Customer requirements analysis, system analysis, concept development, designing, prototyping, testing and validation.

(continues on the next page)



## Re-Scoped Project Plan





- Go/No-go #1 Preliminary Transmission Design Complete. Concept selected, breadboard transmission selected, performance modeled. ✓
- Go/No-go #2 Modular 3 and 4-speed transmission family designed that meets targets and ready to prototype and test.



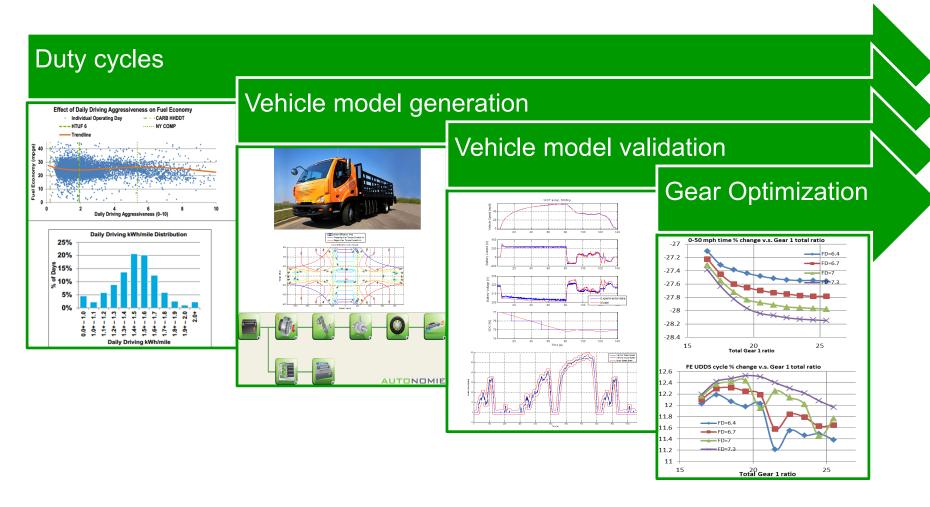
### Milestones, BP2

Date	Milestone and Go/No-Go Decisions	Status
Jan. 2016	Milestone Expanded Transmission Modeling/Simulation	Complete
Apr. 2016	Milestone Transmission layout complete	Complete
Jul. 2016	Milestone Transmission system design complete	In progress
Oct. 2016	Milestone  1st stage of transmission prototyping complete.	On track
Nov. 2016	Go/No-Go Decision Product intend design is complete	On track

- Transmission modeling is extended to other vocations.
- Modular 3 and 4-speed Automated Mechanical Transmission (AMT) family will be designed with a flexibility to meet the needs of electric trucks from Class 2b to 7 (or 8500 lb to 36K lb GVW).



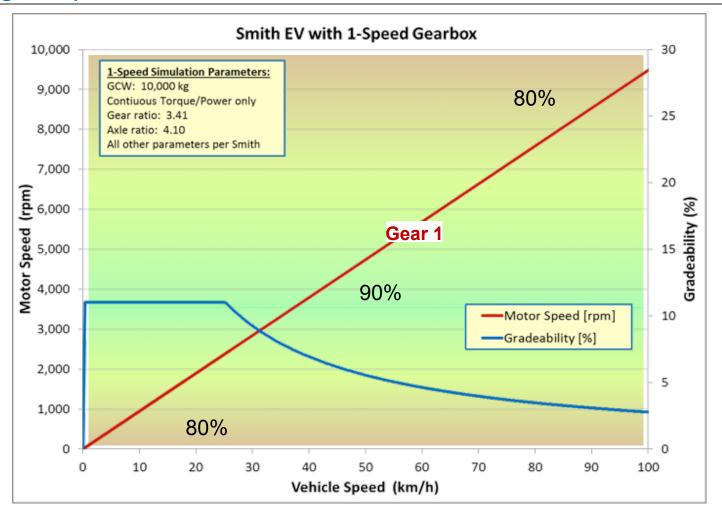
## Technical Progress – Modeling and simulation





# Technical Progress – EV Powertrain Analysis

Single-Speed Transmission

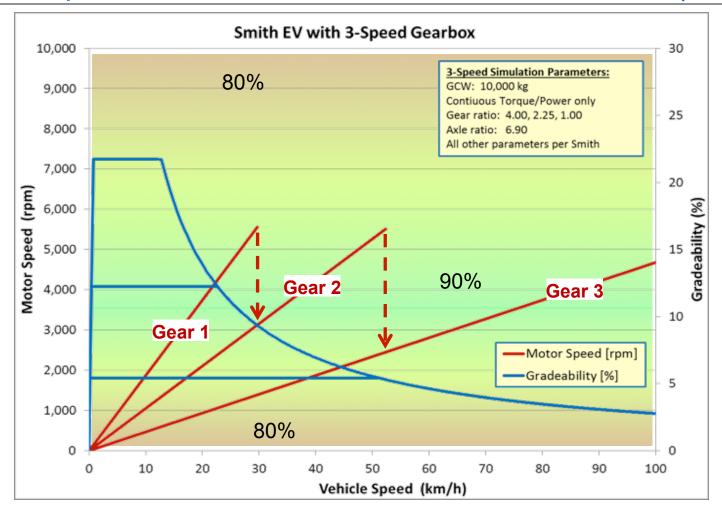


Single-Speed: Motor in "Green Band" only from 30 to 60 km/h



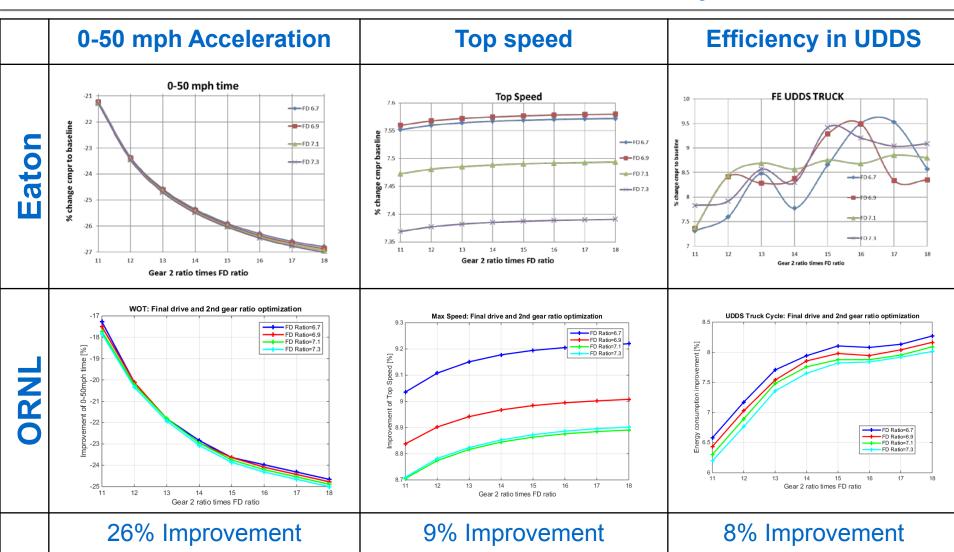
# Technical Progress – EV Powertrain Analysis

Three-Speed Automated Mechanical Transmission (AMT)





# Technical Progress – Performance with AMT on Smith-Newton™ MD-EV Delivery Truck





# Technical Progress – Gear ratios selection for Smith-Newton™ MD-EV Delivery Truck

#### Baseline Smith-Newton™ with SS gearbox:

GCW: 10K lb SS gear ratio: 3.4

GVW: 26K lb Final drive ratio: 4.1

### Recommending 3-speed transmission and a new final drive ratio:

Gear	Ratio	Benefits
1 <sup>st</sup>	4.0	Provides 2X torque to the wheels than SS gear. Provides 23% faster acceleration, 8% better efficiency in the 0-10 mph range and 130% higher gradeability than SS gear.
2 <sup>nd</sup>	2.2	This ratio is equivalent to Smith's single speed gear box and efficient only at 10-25 mph range.
3 <sup>rd</sup>	1.0	Direct drive is the most efficient ratio. Provides 8% better efficiency in the 25 to 65 mph range than SS gear.
Final drive	6.9	This final drive ratio enables efficient direct drive and 9% higher top speed at the top gear.



### Technical Progress – EV Transmission Concept Analysis

- Multiple transmission concepts were developed
- The top 5 concepts were subjected to the trade off analysis based on the performance and business criteria determined earlier in the project.
- The top 5 concepts from high to low ranking:

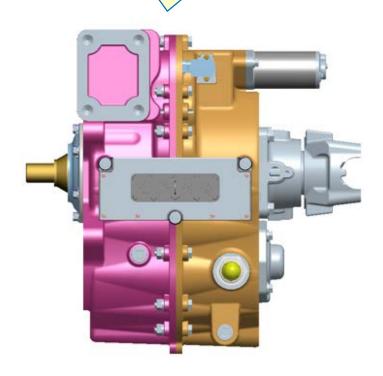
Selected

- 3-4 speed automated mechanical transmission (AMT) family
- 4 speed dry dual clutch transmission
- 4 speed wet dual clutch transmission
- 3 speed planetary automated mechanical transmission
- 3 speed planetary powershift transmission



# Technical Progress – 3 and 4 speed AMTs Design of Flexible Family of EV Transmissions

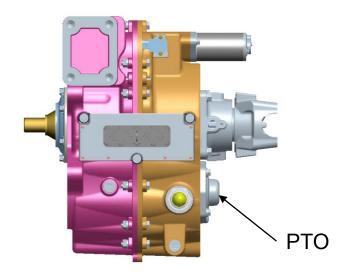
- Up to 1300 Nm (975 lbft), 5000 rpm
- Can be configured as 3 or 4 speed
- Ratio coverage up to 9.0:1
- Flexible design accommodates multiple "gear kits" to cover a wide ratio of vehicle vocations



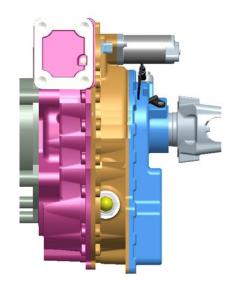


## Technical Progress – Transmission Design

Compact 2, 3, and 4 speed EV Transmission Family



3 and 4-speed AMTs with rear Power Take Off (PTO) option

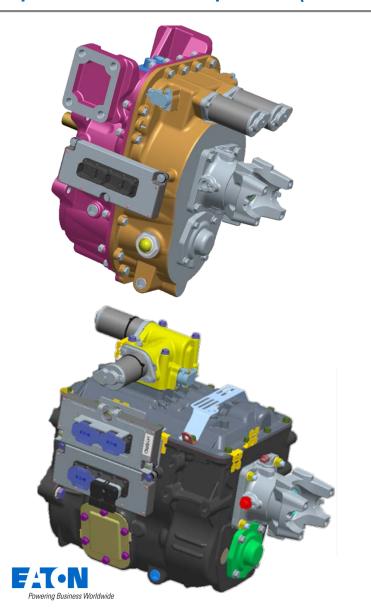


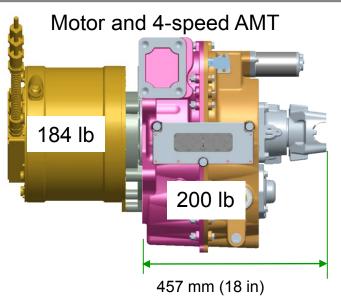
Concept rendering of 2 speed AMT with dry sump lubrication



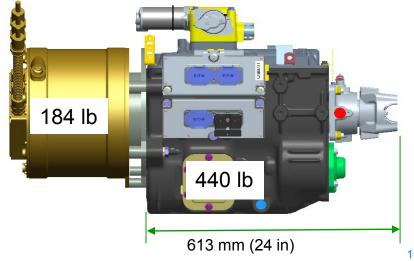
## Technical Progress – Weight and Space claims

Comparison of 6-speed (breadboard) and 4-speed AMT





Motor and 6-speed Hybrid AMT (Breadboard)



# Differences Between Original and Rescoped Plans

	Original Plan Breadboard	Rescoped Plan Product-line-EV-AMT
Gearbox	6-speed hybrid gearbox: modified to be 4-speed by blocking out 2 gears	Modular new design: Flexible to create a family of purpose-built 2, 3, or 4-speed EV-AMTs
Weight and length	440 lb, 24 in	200 lb, 18 in
Shifting mechanism	<ul><li>X-Y shifter</li><li>Complex design</li></ul>	YY shifter: Faster shift; lower cost
Materials	<ul><li>Cast iron housing</li><li>Solid shafts</li></ul>	<ul><li>Aluminum housing - cast or print</li><li>Potential hollow shafts</li></ul>
Controls	Provide TCM, modify MCU	Provide TCM, modify MCU and supervisory power management of EVs



# Responses to Last Year Reviewers' Comments

Question 2: Technical Accomplishments and Progress toward overall project and DOE goals—the degree to which progress has been made, measured against performance indicators and demonstrated progress towards DOE goals.

#### Reviewer 1:

The reviewer stated that deliverable goals are being met. This is a good topic, but the reviewer questioned the EV volumes in this space and the contribution of such a transmission. The reviewer appreciated Eaton and DOE working on this. The reviewer asked if benefits in acceleration and top speed are really needed. The reviewer understood the increase in gradeability and fuel economy, but questioned the results from voice of customer work shared in Slide 11, and suggested this might be validated a bit more.

- The ranking of performance requirements was based on Smith-Newton-26K-GWV experience. Long acceleration time (88 s for 0-50 mph) and low top speed (50 mph) are barriers to entering a highway for Smith-Newton™ and are the result of restricting the motor to continuous power to extend the range. Since the range has already been maximized and the highway usage is not needed the range and the top speed ranked low for Smith-Newton™. However, the slow acceleration is a major problem even in city driving therefore it ranked very high for Smith-Newton™
- The requirements will be ranked again after a new EV-OEM partner is selected.



# Responses to Last Year Reviewers' Comments

#### Reviewer 3:

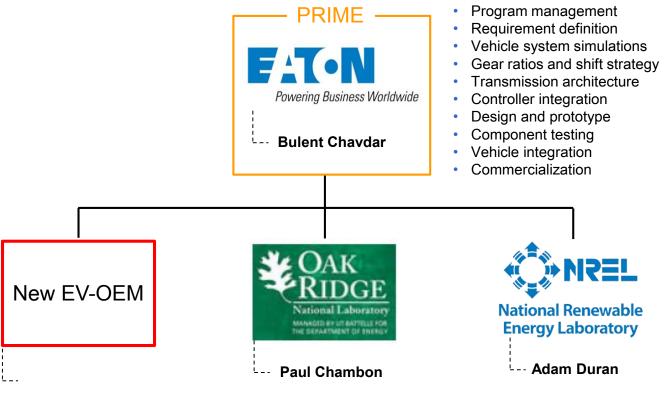
The reviewer noted that the approach taken to analyzing EV transmission volume is misleading because one of the keys to see market penetration is the payback period and cost. Only presenting projection on volume is not enough. The reviewer asked what the y axis for the figures in Slide 10 is and what DFSS (Design for Six Sigma) means. The reviewer said do not assume that all readers can understand all acronyms.

The reviewer said if capital cost and price of transmission would be overwhelmingly important (Slide 11), the cost should have been addressed. However, this has not been done yet.

- The market penetration of MD-EVs to a truck market is different from the market penetration of a transmission into an existing MD-EV market. An EV costs twice an equivalent ICDV. A transmission alone will not be able to change this ratio significantly.
- Electric bus market grows in China fast due to the government regulations and the subsidies. A multi-speed transmission enable downsizing the motor thereby being a cost reducer. In other words an EV customer can have performance benefits in addition to the reduced EV price (2.5% less) with a transmission.
- In the case of using the same motor, the pay back period for adding a multi-speed transmission is estimated to be 4 to 8 years based on 10% increase in energy efficiency.



### Collaborations



- Requirement definition
- Baseline vehicle
- Performance limits of baseline
- Vehicle integration

Relationship: Industry

Subcontractor within VT Program

- Vehicle level simulations
- Component testing
- HIL testing
- General support

Relationship: Federal Laboratory

Subcontractor outside VT Program

- Requirement definition
- Duty cycle harvesting
- Vehicle integration
- Performance testing and demonstration

Relationship: Federal Laboratory

Subcontractor outside VT Program

### Remaining Challenges and Barriers

- We need a new EV OEM partner that will contribute to the integration of transmission with the electric vehicle and facilitate the necessary interactions between the transmission controller and the motor controller.
- An integration partner would consist of selecting an eMotor, inverter, and battery supplier then working with each of the suppliers to ensure the respective components meet Eaton's communication specifications.
- Based on the discussions we have been having with EV-OEMs the vehicle integration issues mentioned above may be of low risk.
- By the time of this presentation we may have already found an EV-OEM partner.



### Proposed Future Work

- BP2 2016 Technology Development , Design, and Prototyping
  - Extended transmission modeling and simulations activities
  - Transmission design
  - Prototype fabrication
- BP3 2017 Technology Integration, Testing, and Demonstration
  - Vehicle integration at Eaton
  - Performing preliminary gearbox testing at Eaton
  - Integrated powertrain hardware in the loop testing at ORNL
  - Integrated vehicle testing at NREL



### Summary

- Project is on schedule. All required project milestones have been met to date.
- MD-EVs will benefit from a 3-speed AMT with the following performance improvements based on Smith-Newton™ platform

Startability: 130%

Acceleration: 23%

Top speed: 9%

Efficiency: 8% on UDDS cycle

- Supervisory power management is needed to double the improvements on acceleration and top speed on Smith-Newton™.
- Modeling and simulations were expanded to a spectrum of vocations and vehicle segments.
- The initial transmission layout design for a 3 and 4 speed AMT family has been completed.
- The EV-Transmission needs to be low cost, modular, and designed with a flexibility to meet the needs of electric trucks from Class 2b to 7 (or 8500 lb to 36K lb GVW).
- There are opportunities for lightweighting (hollow shafts, aluminum housings), and additive manufacturing technologies.





# **2015 DOE Vehicle Technologies Office Annual Merit**

### Technical Backup Slides



# Technical Progress – Target metrics for Smith-Newton™ MD-EV Delivery Truck

						prediction vali	
					baseline ve	ehicle model at	ORNL
		FOA		Project	Smith	Smith	
Characteristic	Units	10t GVW	FOA Targets	Targets	10t GVW	10t GVW	Improvem
Cilaracteristic	Ullits	Baseline	l OA laigets	Baseline with	Baseline with	Baseline with	ent
		with SS		MS Trans.	SS gearbox	3-spd AMT	
Top speed with power limitations without power limitations	mph	50	65+	65+	54.5 59.1	59.3 70.0	8.8% 18.4%
Energy efficiency on UDDS	mpge	37	>5%	8%	29.6	32.1	7.7%
or range improvement on CILCC	111990	50	7,0	0 70	41.7	42.9	2.9%
Acceleration (0-30 mph)	s			15	18.8	18.9	-0.5%
Acceleration (30-50 mph)	S		Ingrasad	30	69.2	48.7	29.6%
Acceleration (0-50 mph) w pwr limits	0		Increased acceleration	45	88.0	67.6	23.2%
w/o power limits	S		acceleration	45	25.4	24.4	3.9%
Gradeability (top speed on 2% grade)	mph				38.8	41.3	6.4%
Startability (Max. grade on which vehicle launching from rest allows motor to reach max. power in 3 s)	% grade		Quickly accelerate and climb	50% improvement over baseline	9.8%	22.5%	130%
Reliability (B10 life)	miles				warr. 3yr/36K	400K	
Gearbox efficiency	%	93.4		98	93.4	98	5%
Gearbox weight	lb				60	200	-333%
System weight: gearbox/motor	lb				244	384	-57%
Gearbox dimensions (HxWxL)	in				14.4x11x9.1	21x19x19	-526%
System (G/M) dimensions	in				18x13.7x20	21x19x30	-243%



Performance prediction validated by

### Dry-Sump vs Wet-Sump Churning Loss Study

- Eaton's Transmission Descriptive Language tool (TDL) was used to simulate oil churning and calculate losses at various input speeds
- Eaton PS-386 Synthetic Transmission Oil was used for this study
  - Properties were derived at 100°C
- Five oil levels were studied
  - Studies 3 & 5 were used for wet/dry sump comparisons

Element:		Oil - Oil	
Property Name	Value	Units	
name	Oil	-	
rho	812.0	kg/m^3	
vk	14.8	cSt (mm^2/s)	
ď	0.1149		
oilVolume	0.00535	m^3	
oilLevelToCenterLine	145.0	mm	
<del>0</del> p	2100.0	J/(Kg*K)	

- TDL Oil Inputs:
  - Density (rho)
  - Viscosity (vk)
  - Oil Mass (oilVolume)
  - Oil Level (oilLevelToCenterLine)



Study #	Oil level (From Center of Main Shaft)	Speed	Churning Losses kW
Š	,	1000	0.4323
1	Center of Main Shaft - Wet Sump	2000	1.1052
'	(0 mm)	3500	2.212
		5000	3.4425
		1000	0.3024
2	Midway between shafts - Wet Sump (72.5 mm)	2000	0.7678
2		3500	1.5368
		5000	2.3917
		1000	0.1965
3	Midway between shafts - Wet Sump (119 mm)	2000	0.4924
		3500	0.9856
		5000	1.5339
		1000	0.153
4	Center of Counter Shaft - Dry Sump (145 mm)	2000	0.3946
7		3500	0.7898
		5000	1.2291
	Bottom of Bearing - Dry Sump	1000	0.0725
5		2000	0.1886
	(187.5 mm)	3500	0.3374
		5000	0.5873

# Dry-Sump vs Wet-Sump Churning Loss Study Conclusion

### Dry-sump lubrication with oil pump is not recommended

- Nominal e-motor operation assumed at 100 kW and 3500 rpm ave.
- A dry-sump would improve nominal operating efficiency by 0.5%.
  - 549 W improvement in loss reduction at nominal operation
- Minimal efficiency reduction observed does not justify the significant added cost, design complexity, and system risk
- Eaton's new PS-386 oil improves gear efficiency while reducing churning loss

### Wet-sump lubrication

- Can adequately dissipate heat (All Eaton MD AMTs use wet sump)
- 119 mm from centerline of main shaft
- Total churning losses at nominal speed (3500 rpm): ~1 kW





